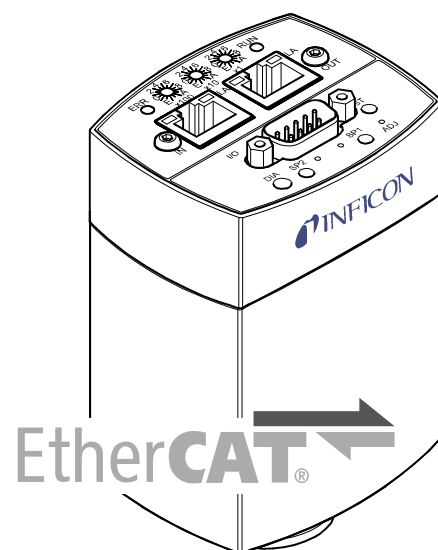


EtherCAT[®]

for Pirani Capacitance Diaphragm and Pirani Standard Gauges

PCG550, PCG552, PCG554,
PSG550, PSG552, PSG554



General Information

Caution

Caution: data transmission errors

Any attempt to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port may result in incorrect data and data transmission errors.

Therefore, it is inadmissible to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface, or the diagnostic port.

Intended Use

This Communication Protocol contains instructions for operating EtherCAT interfaces (slaves) together with a master.



For safety information, specifications and operation instructions of the vacuum gauges refer to the appropriate documents (→ [1], [2]).

EtherCAT-Interface

The following description of the EtherCAT interface is compliant to the EtherCAT specification of the EtherCAT Technology Group (ETG) and to the "EtherCAT Semiconductor Device Profile".

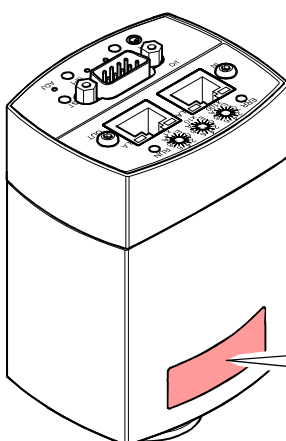
This manual describes the functionality of a EtherCAT slave and supports

- ETG.5003.1 S (R) V1.0.0 : Part 1 Common Device Profile (CDP) (→ [11]) and
- ETG.5003.2080 S (R) V1.0.0 : Part 2080: Specific Device Profile (SDP): Vacuum Pressure Gauge (→ [12]).

We reserve the right to make technical changes without prior notice.

Product Identification

In all communications with INFICON, please specify the information on the product nameplate. For convenient reference copy that information into the space provided below.



INFICON AG, LI-9496 Balzers		
Model:		
PN:		
SN:		
..... V W	

Validity

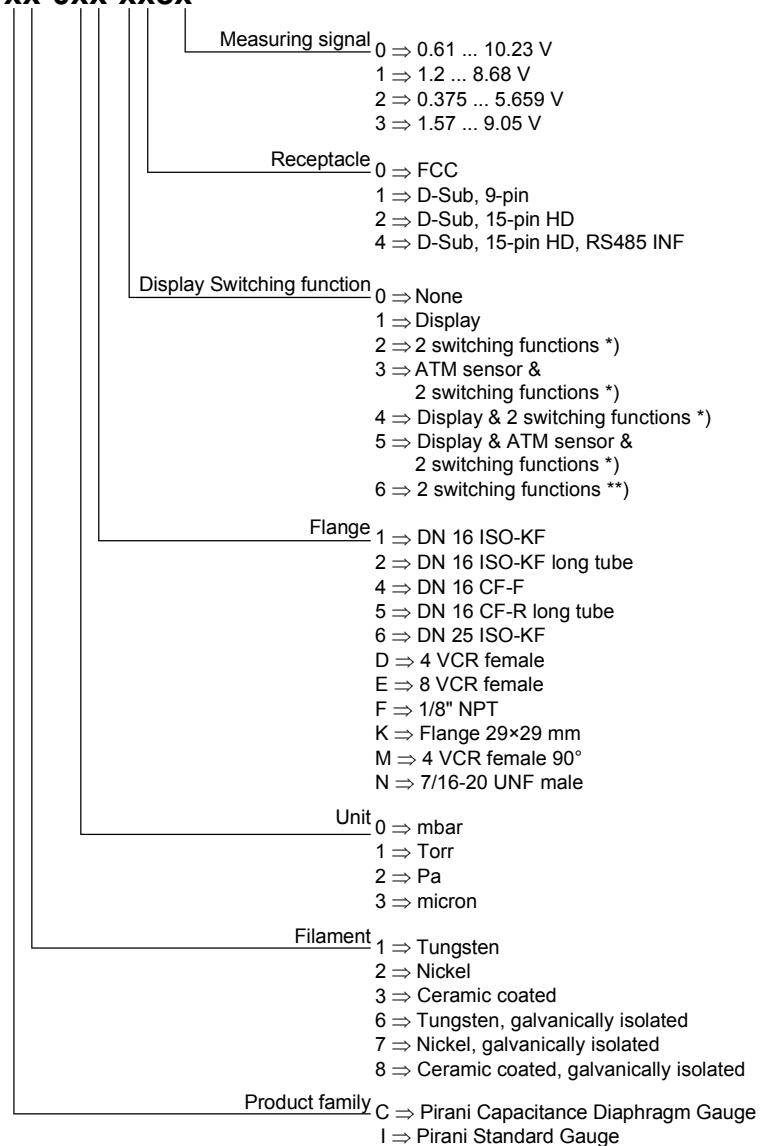
This document applies to products of the Pirani Capacitance Diaphragm (PCG550, PCG552, PCG554) and Pirani Standard Gauges (PSG550, PSG552, PSG554) with EtherCAT interface.

This manual is based on firmware version 1.2.0.0.

If your unit does not work as described in this document, please check that it is equipped with the above firmware version (→ 12 Index: 0x100A Subindex: 0x00).

Part numbers of standard products are indicated below. OEM products have other part numbers and different parameter settings (e.g. factory setting of setpoint) as defined in the corresponding ordering information.

3Pxx-0xx-xx8x



*) Solid state relay

***) Electromechanical relay

The part number (PN) can be taken from the product nameplate.

If not indicated otherwise in the legends, the illustrations in this document correspond to PCG550 gauges with the DN 16 ISO-KF vacuum connection. They apply to other vacuum connections and to the other gauges by analogy.

We reserve the right to make technical changes without prior notice.

Trademark

EtherCAT® Beckhoff Automation GmbH, Deutschland



Patents

EP 0689669 B1, 0689670 B1, 0658755 B1
US Patents 5608168, 4031997, 5583297

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For cross-references within this document, the symbol (→  XY) is used, for cross-references to further documents, listed under literature, the symbol (→  [Z]).

1 Technical Data

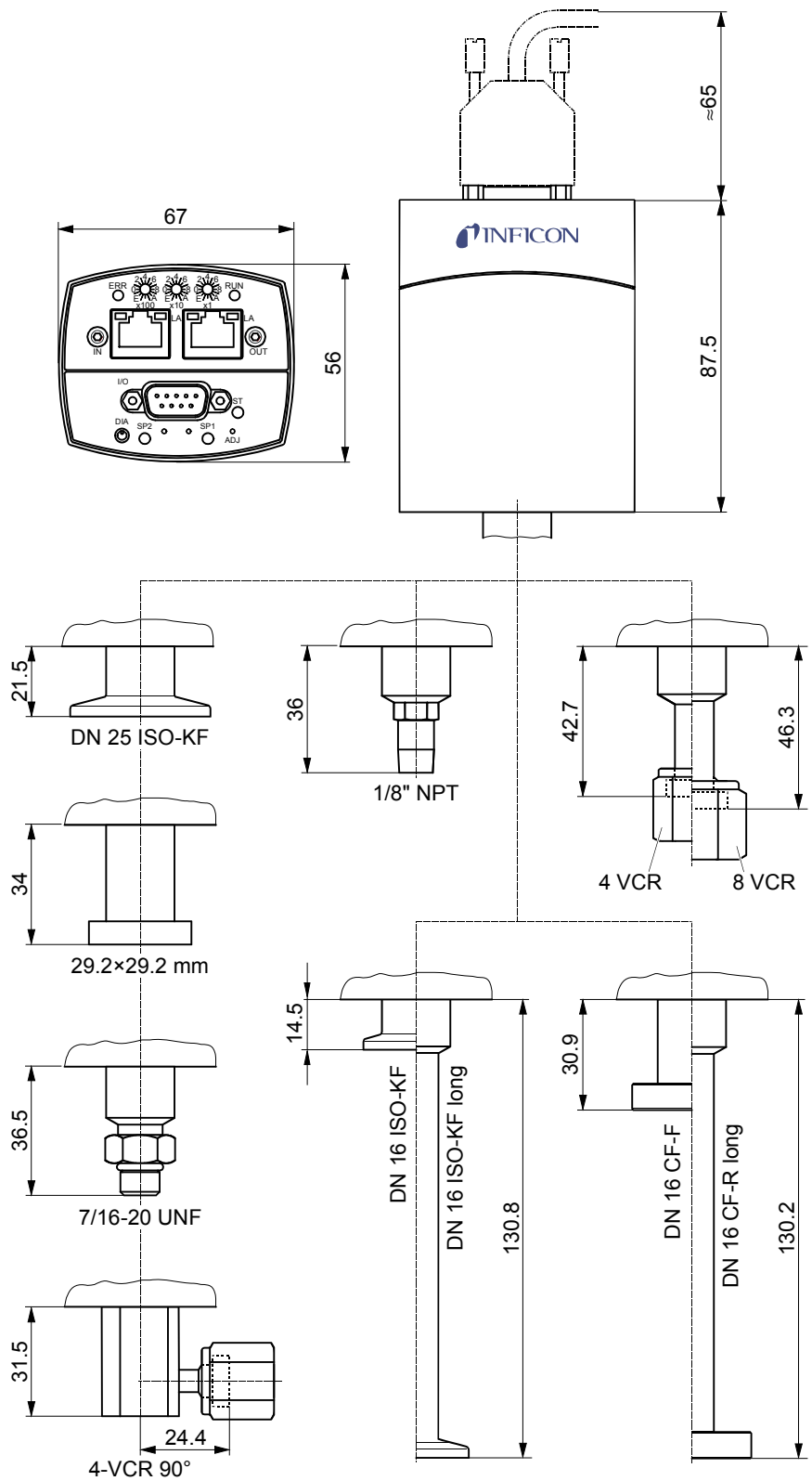


Further technical data →  [1], [2].

EtherCAT interface

Communication protocol	protocol specialized for EtherCAT
Communication standards	ETG.5003.1: Part 1 Common Device Profile (CDP) (→  [11]) ETG.5003.2080: Part 2080 Specific Device Profile (SDP): Vacuum Pressure Gauge (→  [12])
Data rate	100 Mbps
Node address	Explicit Device Identification
Physical layer	100BASE-Tx (IEEE 802.3)
EtherCAT connector	2 × RJ45, 8-pin (socket) <IN>: EtherCAT input <OUT>: EtherCAT output
Cable	special Ethernet Patch Cable (CAT5e quality or higher), shielded
Cable length	≤100 m
<hr/>	
Process data	Fixed PDO mapping and configurable PDO mapping
Mailbox (CoE)	SDO requests, responses and information
<hr/>	

Dimensions [mm]



2 Interface Connection

Making an EtherCAT interface cable

For operating the Pirani Standard (PSG55x) or Pirani Capacitance Diaphragm (PCG55x) Gauge via EtherCAT, two interface cables conforming to the EtherCAT standard are required.

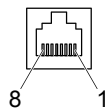
If no such cables are available, make two according to the following indications.

Cable type

Ethernet Patch Cable (CAT5e quality) with FCC68 connector.

Procedure

1 Pin assignment:

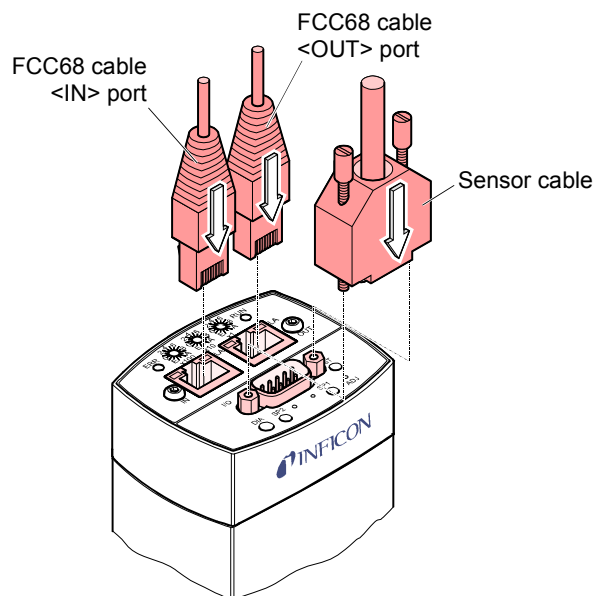


FCC68, 8-pin, male, soldering side

Pin	Signal	Description
1	TD+	Transmission Data +
2	TD-	Transmission Data -
3	RD+	Receive Data +
4	nu	not used
5	nu	not used
6	RD-	Receive Data -
7	nu	not used
8	nu	not used

Pin assignment of the D-Sub 15-pin sensor connector according to the respective operating manual (→ [1], [2]).

2 Plug the EtherCAT (and sensor) cables connector into the gauge: From the previous device the cable connected to OUT port has to be connected to the PxG55x <IN> port. And the cable from the PxG55x <OUT> port has to be connected to the next device's <IN> port.



3 Operation

3.1 Introduction

Via the EtherCAT interface, the following and further data are exchanged in the standardized EtherCAT protocol:

- Pressure reading
- Pressure unit (Torr, mbar, Pa)
- Zero adjustment
- Status and error messages
- Status of the switching functions
- Set Trip Point for switching functions



Caution

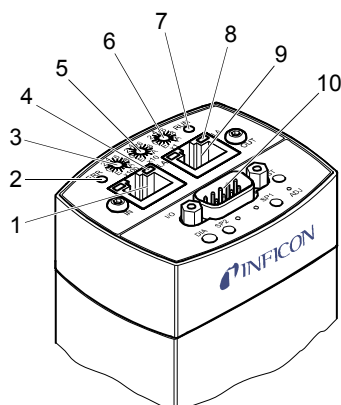


Caution: data transmission errors

Any attempt to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port may result in incorrect data and data transmission errors.

Therefore, it is inadmissible to simultaneously operate the gauge via the RS232C Serial Interface and EtherCAT interface or the diagnostic port.

3.2 Front View



Position	Label	Function
1	IN	EtherCAT IN connector
2	ERR	Error LED
3	x100	Address Switch × 100, hexadecimal
4	LA	Link activity EtherCAT IN
5	x10	Address Switch × 10, hexadecimal
6	x1	Address Switch × 1, hexadecimal
7	RUN	EtherCAT Status LED
8	LA	Link activity EtherCAT OUT
9	OUT	EtherCAT OUT connector
10	PWR	Sensor cable connector (Power, analog I/O, RS232C I/O and Relay contacts)

3.3 Indicators and Switches

3.3.1 <RUN> LED



Displays the operating status.

Color	LED State	Description
green	off	INIT (initialization status) or no power applied to device.
	blinking (200 ms on 200 ms off)	PREOP (pre-operational status).
	single flash (200 ms on 1000 ms off)	SAFEOP (safe-operational status). Communication of cyclic data transfer running. Input values available, output values written to the device but not updated on device output.
	on	OP (operational status).

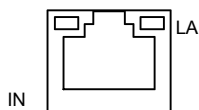
3.3.2 <ERR> LED



Displays the error content.

Color	LED State	Description
red	off	No error or no power applied to device.
	blinking (200 ms on 200 ms off)	Error occurred (see error parameter).
	single flash (200 ms on 1000 ms off)	Slave device application has changed the EtherCAT state autonomously, due to local error (see error parameter).
	double flash (200 ms on 200 ms off 200 ms on 1000 ms off)	An application watchdog timeout has occurred. Sync Manager Watchdog timeout or communication timeout occurred.
	on	A critical communication or application controller error has occurred. Application controller is not responding any more (PDI Watchdog Timeout detected by ESC)

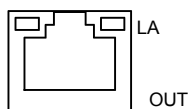
3.3.3 <LA> LED (<IN> Port)



Displays the input status.

Color	LED State	Description
green	off	Port not connected or no power applied to device.
	blinking	Port connected and communication active.
	on	Port not connected but no communication.

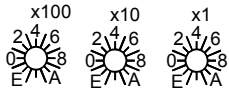
3.3.4 <LA> LED (<OUT> Port)



Displays the output status.

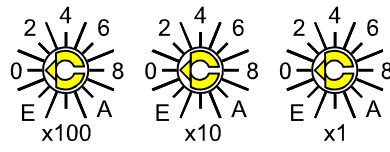
Color	LED State	Description
green	off	Port not connected or no power applied to device.
	blinking	Port connected and communication active.
	on	Port not connected but no communication.

3.3.5 Device Address Switch



During device initialization, the device address switches are read by the device firmware. This device address is supported to the master as Explicit Device Identification.

Example: Value of the Explicit Device ID = 0xDDD (dec 3549):
 $0x100 * 0xD$ (dec 3328) + $0x10 * 0xD$ (dec 208) + $0x1 * 0xD$ (dec 13)



4 Object Structure

This chapter describes the CANopen over EtherCAT (CoE) Object Dictionary.

4.1 Object Dictionary structure

The objects in the CoE Object Dictionary can be accessed with SDO services, and many of the dictionary objects can be mapped for cyclic communication in PDOs. Each object is addressed using a 16-bit index and an 8-bit subindex.

The following table presents the overall layout of the standard Object Dictionary.

Index (hex.)	Object dictionary area	
1000 – 1FFF	Communication profile area	
2000 – 5FFF	Manufacturer-specific profile area	
6000 – 6FFF	Profile Specific Area	Input area
7000 – 7FFF		Output area
8000 – 8FFF		Configuration area
9000 – 9FFF		Information area
A000 – AFFF		Diagnosis area
B000 – BFFF		Service Transfer area
C000 – EFFF		Reserved area
F000 – FFFF		Device area

Explanations for the abbreviations in the columns of the tables are given below:

Abbr.	Description
Access	SDO read/write access <ul style="list-style-type: none"> RO: object can only be read by the SDO service RW: object can be both read and written by the SDO service
CoE	CAN application protocol over EtherCAT
Index	Object Index (hex.) (address of an object)
NV	Nonvolatile; attribute value is maintained through power cycles
Object	Abstract representation of a particular component within a device, which consists of data, parameters, and methods.
PDO	Process Data Object. Structure described by mapping parameters containing one or several process data entities.
PM	PDO mapping <ul style="list-style-type: none"> Rx: object can be mapped into an Rx PDO Tx : object can be mapped into a Tx PDO
RxPDO	Receive PDO. A Process Data Object received by an EtherCAT slave.
SDO	Service Data Objects. CoE asynchronous mailbox communications where all objects in the Object Dictionary can be read and written.
SI	Subindex (hex.) (sub-address of an object)
Type	Data Type <ul style="list-style-type: none"> BOOL, BIT = 1 bit. Boolean (0 = false, 1 = true) USINT, BYTE = 8 bit. Unsigned Byte UINT = 16 bit. Unsigned integer value UDINT = 32 bit. Unsigned integer value ULINT = 64 bit. Unsigned integer value REAL = 32 bit. Floating point V_STRING = 8×n bit. Visible string (1 byte for character)
TxPDO	Transmit PDO. A Process Data Object sent from an EtherCAT slave.

4.2 Communication Profile Objects (0x1000...0x1FFF)

The objects of the communication profile describe the basic EtherCAT properties of the PxG55x and are common to all EtherCAT slaves using the CoE communication protocol. The objects are described in following table:

Index	SI	DataType	NV	Access	PM	Name
1000		UDINT		RO		Device Type
1008		V_STRING		RO		Manufacturer Device name
1009		V_STRING		RO		Manufacturer Hardware Version
100A		V_STRING		RO		Manufacturer Software Version
1010	0x01	UDINT		RW		<p>Store Parameters</p> <p>Read: Bit 0 = 1: slave saves the backup entries when writing 0x1010:01 with 0x65766173</p> <p>Bit 1 = 1: slave saves the backup entries automatically when they are written</p> <p>Bit 2-31 = 0</p> <p>Write: With the value 0x65766173 the backup entries will be stored to non-volatile memory of the slave</p>
1011	0x01	UDINT		RW		<p>Restore Default Parameters</p> <p>Read: Bit 0 = 1: slave supports the restoring of backup entries with the default values when writing 0x1011:01 with 0x64616F6C</p> <p>Bit 1-31 = 0</p> <p>Write: With the value 0x64616F6C the backup entries will be restored with the default values</p>
1018				RO		Identity Object
	0x01	UDINT		RO		Vendor ID
	0x02	UDINT		RO		Product Code
	0x03	UDINT		RO		Revision Number
	0x04	UDINT		RO		Serial Number
10F8		ULINT		RO		Timestamp Object

4.2.1 Process Data Objects (PDO's)

- PSG gauges: They consist of one vacuum pressure sensor.
- PCG gauges with or without ATM: They consist of two vacuum pressure sensors. The characteristic of this combi device is that only one vacuum pressure sensor outputs an actual pressure value at one time. The other sensor is in overrange condition which means that the pressure is higher than the measurement range of the sensor or underrange condition which means that the pressure is lower than the measurement of the sensor. The 'Combination Gauge Active Value' outputs the pressure value from the active measuring sensor.

For each sensor module a default mapping is configured. The mapping for each sensor module has the same contents. For a compact cyclic data frame duplicated mappings can be deactivated.

Or to meet other requirements the TxPDO's 1A01, 1A03 or 1A05 and the RxPDO 1601 are designated for user mapping. These PDO's do not have default values and can be set up by the PDO configuration.

RxPDO's

Index	SI	Data Type	NV	Access	PM	Name
1600		PM		RW		RxPDO Receive PDO Mapping,
1601		PM		RW		RxPDO Receive PDO Mapping, User Mapping

TxPDO's PSG

Index	SI	Data Type	NV	Access	PM	Name
1A00		PM		RW		TxPDO Transmit PDO Mapping
	0x01	BIT				Reading Valid
	0x02	BIT				Overrange Exceeded
	0x03	BIT				Underrange Exceeded
	0x04	BIT				Padding Bits 1 (5 bit)
	0x05	REAL				Sensor Value
	0x06	UDINT				Trip Point Output All Instance
1A01		PM		RW		TxPDO Transmit PDO Mapping, User Mapping

TxPDO's PCG (PCG with or without ATM only)

Index	SI	Data Type	NV	Access	PM	Name
1A00 or 1A02 or 1A04		PM		RW		TxPDO Transmit PDO Mapping
	0x01	BIT				Combination Gauge Reading Valid
	0x02	BIT				Combination Gauge Overrange Exceeded
	0x03	BIT				Combination Gauge Underrange Exceeded
	0x04	BIT				Padding Bits 1 (5 bit)
	0x05	REAL				Combination Gauge Active Value
	0x06	UDINT				Trip Point Output ALL Instance
1A01 or 1A03 or 1A05		PM		RW		TxPDO Transmit PDO Mapping, User Mapping

Sync Manager

Index	SI	Data Type	NV	Access	PM	Name
1C00	0x01 0x02 0x03 0x04	BYTE		RW		Sync Manager Type
1C12 / 1C13	0x01 0x02 0x03 0x04	UINT		RW		Sync Manager PDO Assignment
1C32 / 1C33	0x01 - 0x20			RW		Sync Manager Parameter

4.3 Manufacturer-specific Profile Objects (0x2000...0x5FFF)

The manufacturer-specific profile objects contain the manufacturer's model number and device configuration data, status and diagnostic data. The objects are described in the following tables.

4.3.1 Manufacturer Configuration Module 1

- PCG gauges with or without ATM: The "Manufacturer Configuration Module 1" is assigned to the CDG module.
- PSG gauges: The "Manufacturer Configuration Module 1" is assigned to the Pirani module.

Index	SI	Data Type	NV	Access	PM	Name
4000	0x01	BYTE		RW		Safe State
	0x02	REAL		RW		Safe Value

Subindex 0x01

Specifies the behavior for the value for States other than Valid.

Safe State	
0	Zero
1	Full Scale
2	Hold last value
3	Use safe value

Subindex 0x02

Safe Value: The value to be used for Safe State = Safe Value.

4.3.2 Manufacturer Configuration Module 2 (PCG with or without ATM only)

- PCG gauges with ATM: The "Manufacturer Configuration Module 2" is assigned to the ATM module.
- PCG gauges without ATM: The "Manufacturer Configuration Module 2" is assigned to the Pirani module.

Index	SI	Data Type	NV	Access	PM	Name
4010	0x01	BYTE		RW		Safe State
	0x02	REAL		RW		Safe Value

Subindex 0x01

Specifies the behavior for the Value for states other than Valid.

Safe State	
0	Zero
1	Full Scale
2	Hold last value
3	Use safe value

Subindex 0x02

Safe Value: The value to be used for Safe State = Safe Value.

4.3.3 Manufacturer Configuration Module 3 (PCG with ATM only)

- PCG gauges with ATM: The "Manufacturer Configuration Module 3" is assigned to the Pirani module.

Index	SI	Data Type	NV	Access	PM	Name
4020	0x01	BYTE		RW		Safe State
	0x02	REAL		RW		Safe Value

Subindex 0x01

Specifies the behavior for the Value for states other than Valid.

Safe State	
0	Zero
1	Full Scale
2	Hold last value
3	Use safe value

Subindex 0x02

Safe Value: The value to be used for Safe State = Safe Value.

4.4 Input Area PCG with ATM (0x6000...0x6FFF)

4.4.1 Input Common

Index	SI	Data Type	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.4.2 Input Capacitance Diaphragm

Index	SI	Data Type	NV	Access	PM	Name
6001	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.4.3 Input Common

Index	SI	Data Type	NV	Access	PM	Name
6010	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.4.4 Input Piezo

Index	SI	Data Type	NV	Access	PM	Name
6012	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.4.5 Input Common

Index	SI	Data Type	NV	Access	PM	Name
6020	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.4.6 Input Heat Transfer

Index	SI	Data Type	NV	Access	PM	Name
6023	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.4.7 Input Trip Point 1

Index	SI	Data Type	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.4.8 Input Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.5 Input Area PCG without ATM (0x6000...0x6FFF)

4.5.1 Input Common

Index	SI	DataType	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.5.2 Input Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
6001	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.5.3 Input Common

Index	SI	Data Type	NV	Access	PM	Name
6010	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.5.4 Input Heat Transfer

Index	SI	Data Type	NV	Access	PM	Name
6013	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.5.5 Input Trip Point 1

Index	SI	Data Type	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.5.6 Input Trip Point 2

Index	SI	DataType	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.6 Input Area PSG (0x6000...0x6FFF)

4.6.1 Input Common

Index	SI	DataType	NV	Access	PM	Name
6000	0x0E	BOOL		RO	tx	TxPdoState
	0x11	REAL		RO	tx	Sensor Value

Subindex 0x0E

Is set if the device is not in Safe State (value (I 0x6nn0, SI 0x11) = valid)

TxPdoState	
0	Invalid
1	Valid

Subindex 0x11

The corrected, converted, calibrated final analog input value of the sensor.

4.6.2 Input Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
6003	0x01	BOOL		RO	tx	Reading Valid
	0x02	BOOL		RO	tx	Overrange Exceeded
	0x03	BOOL		RO	tx	Underrange Exceeded

Subindex 0x01

Indicates whether the Value parameter contains a valid value within the specified accuracy or not.

Reading Valid	
0	Invalid
1	Valid

Subindex 0x02

Indicates whether the Value parameter contains a value in over range.

Reading Valid	
0	No Overrange Exceeded
1	Overrange Exceeded

Subindex 0x03

Indicates whether the Value parameter contains a value in under range.

Reading Valid	
0	No Underrange Exceeded
1	Underrange Exceeded

4.6.3 Input Trip Point 1

Index	SI	Data Type	NV	Access	PM	Name
600E	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.6.4 Input Trip Point 2

Index	SI	Data Type	NV	Access	PM	Name
600F	0x01	BOOL		RO	tx	Status High Trip
	0x02	BOOL		RO	tx	Status Low Trip

Subindex 0x01

Status High Trip	
0	High Trip not assert
1	High Trip assert

Subindex 0x02

Status Low Trip	
0	Low Trip not assert
1	Low Trip assert

4.7 PCG with ATM Configuration Area (0x8000...0x8FFF)

This chapter describes the configuration area of the PCG with ATM.

4.7.1 Configuration Common Module

Calculating the High Trip Point and Low Trip Point → 4.4.7.

Index	SI	Data Type	NV	Access	PM	Name
8000 or 8010 or 8020	0x01	REAL32	x	RW		Cross Over Area Upper Limit
	0x02	REAL32	x	RW		Cross Over Area Lower Limit

Subindex 0x01

Upper limit of the cross over area.



At low pressures, only the signal of the Pirani sensor is used for pressure measurement; at high pressures, only the signal of the diaphragm capacitive sensor. To determine the output signal in the cross over area, both signals are used proportionally to the pressure.

Subindex 0x02

Lower limit of the cross over area.

4.7.2 Configuration Capacitance Diaphragm

Subindex 0x01

Index	SI	DataType	NV	Access	PM	Name
8001	0x01	REAL	x	RW		Zero Adjust Mode

The CDG Sensor is adjusted automatically by the Pirani sensor, if this index is set.

4.7.3 Configuration Trip Point 1

The High Trip Point is calculated by:

$$\text{High Trip Point} = \text{Value}^{*)} \times \text{Percentage}^{**)}$$

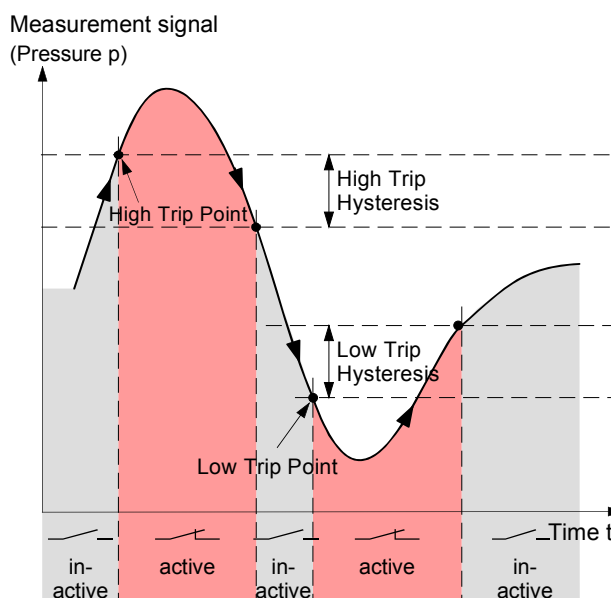
*) Value from Piezo Sensor (I: 0x6010, SI: 0x11)

**) Percentage High Trip Source (I: 0x800E/F, SI: 0x13)

In this case, the High Trip Point value is automatically updated by the device itself. Any user-written value to the parameter High Trip will be refused with an abort code.

The Low Trip Point is a fixed value:

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	DataType	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800E1100 (High Trip Point Limit).

For ATM Mode set value to 0x800E1300 (Percentage High Trip Source).

Subindex 0x13

Percentage of High Trip Source: Percentage of Piezo Sensor Value (I 0x6010, SI 0x11) in [%].

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800E1400.

For ATM Mode set value to 0x800E1600.

Subindex 0x16

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0x900E SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

Is set to Combi Gauge Value 0xF6401100.

4.7.4 Configuration Trip Point 2

Calculating the High Trip Point and Low Trip Point → 4.4.7.

Index	SI	Data Type	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x13	REAL	x	RW		Percentage High Trip Source
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point	
0	Disable
1	Enable

Subindex 0x11

High Trip Point limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1100 (High Trip Point Limit).

For ATM Mode set value to 0x800F1300 (Percentage High Trip Source).

Subindex 0x13

Percentage of High Trip Source: Percentage of Piezo Sensor Value (I 0x60010, SI 0x11) in [%].

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1400.

For ATM Mode set value to 0x800F1600.

Subindex 0x16

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0x900F SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

4.8 PCG without ATM, Configuration Area (0x8000...0x8FFF)

This chapter describes the configuration area for the PCG without ATM.

4.8.1 Configuration Common Module

Calculating the High Trip Point and Low Trip Point → 4.4.7.

Index	SI	Data Type	NV	Access	PM	Name
8000 or 8010	0x01	REAL32	x	RW		Cross Over Area Upper Limit
	0x02	REAL32	x	RW		Cross Over Area Lower Limit

Subindex 0x01

Upper limit of the cross over area.



At low pressures, only the signal of the Pirani sensor is used for pressure measurement; at high pressures, only the signal of the diaphragm capacitive sensor. To determine the output signal in the cross over area, both signals are used proportionally to the pressure.

Subindex 0x02

Lower limit of the cross over area.

4.8.2 Configuration Capacitance Diaphragm

Index	SI	Data Type	NV	Access	PM	Name
8001	0x01	REAL	x	RW		Zero Adjust Mode

Subindex 0x01

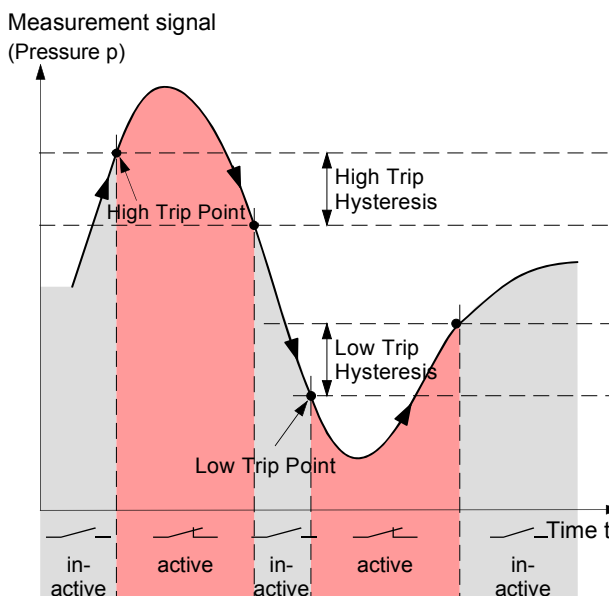
If set the CDG Sensor will be adjusted automatically through the Pirani sensor.

4.8.3 Configuration Trip Point 1

The High Trip Point is a fixed value:

The Low Trip Point is a fixed value:

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	Data Type	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point	
0	Disable
1	Enable

Subindex 0x11

High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800E1100 (High Trip Point Limit).

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800E1400.

Subindex 0x17 High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18 Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A Object index of active source of (I 0x900E SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

Is set to Combi Gauge Value 0xF6401100

4.8.4 Configuration Trip Point 2

Calculating the High Trip Point and Low Trip Point → 4.4.7.

Index	SI	Data Type	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x16	REAL	x	RW		Percentage Low Trip Source
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point	
0	Disable
1	Enable

Subindex 0x11

High Trip Point limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1100 (High Trip Point Limit).

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1400.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

Object index of active source of (I 0x900F SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

4.9 PSG Configuration Area (0x8000...0x8FFF)

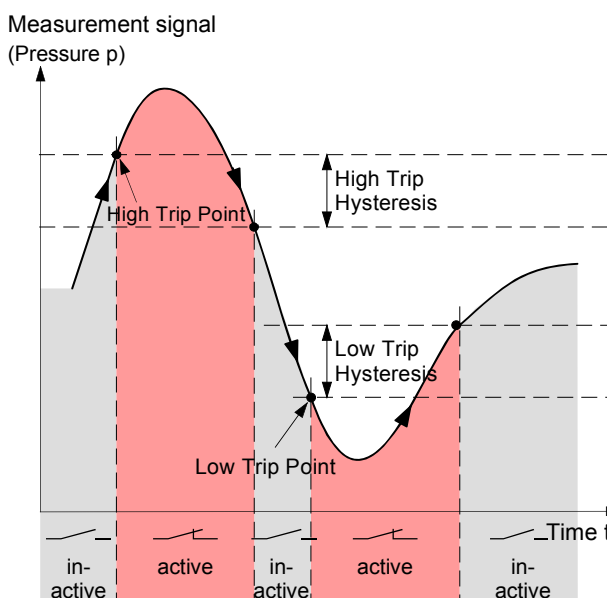
This chapter describes the configuration area for the PSG.

4.9.1 Configuration Trip Point 1

The High Trip Point is a fixed value

The Low Trip Point is a fixed value:

The value defined in Low Trip Point Limit is compared with the pressure value referenced by the Source Index parameter.



Index	SI	DataType	NV	Access	PM	Name
800E	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01	High Trip Point	
	0	Disable
	1	Enable

Subindex 0x02	Low Trip Point	
	0	Disable
	1	Enable

Subindex 0x11 High Trip Point Limit: High limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is above this limit.

Subindex 0x12 Object index of High Trip Point Value source.
 Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved
 For a fix limit set value to 0x800E1100 (High Trip Point Limit).

Subindex 0x14 Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900E, SI 0x01) is below this limit.

Subindex 0x15 Object index of Low Trip Point Value source.
 Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved
 For a fix limit set value to 0x800E1400.

Subindex 0x17 High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18 Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A Object index of active source of (I 0x900E SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

Is set to Combi Gauge Value 0xF6401100.

4.9.2 Configuration Trip Point 2

Calculating the High Trip Point and Low Trip Point → 4.4.7.

Index	SI	Data Type	NV	Access	PM	Name
800F	0x01	BOOL	x	RW		High Trip Enable
	0x02	BOOL	x	RW		Low Trip Enable
	0x11	REAL	x	RW		High Trip Point Limit
	0x12	UDINT	x	RW		High Trip Source Index
	0x14	REAL	x	RW		Low Trip Point Limit
	0x15	UDINT	x	RW		Low Trip Source Index
	0x17	REAL	x	RW		High Trip Hysteresis
	0x18	REAL	x	RW		Low Trip Hysteresis
	0x1A	UDINT	x	RW		Source Index

Subindex 0x01

High Trip Point	
0	Disable
1	Enable

Subindex 0x02

Low Trip Point	
0	Disable
1	Enable

Subindex 0x11

High Trip Point limit: High limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is above this limit.

Subindex 0x12

Object index of High Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1100 (High Trip Point Limit).

Subindex 0x14

Low Trip Point Limit: Low limit to trigger trip point condition if Input Value (I 0x900F, SI 0x01) is below this limit.

Subindex 0x15

Object index of Low Trip Point Value source.

Bit 16...31: Index
 Bit 08...15: Subindex
 Bit 00...07: reserved

For a fix limit set value to 0x800F1400.

Subindex 0x17

High Trip Hysteresis: Hysteresis value for High Trip Point.

Subindex 0x18

Low Trip Hysteresis: Hysteresis value for Low Trip Point.

Subindex 0x1A

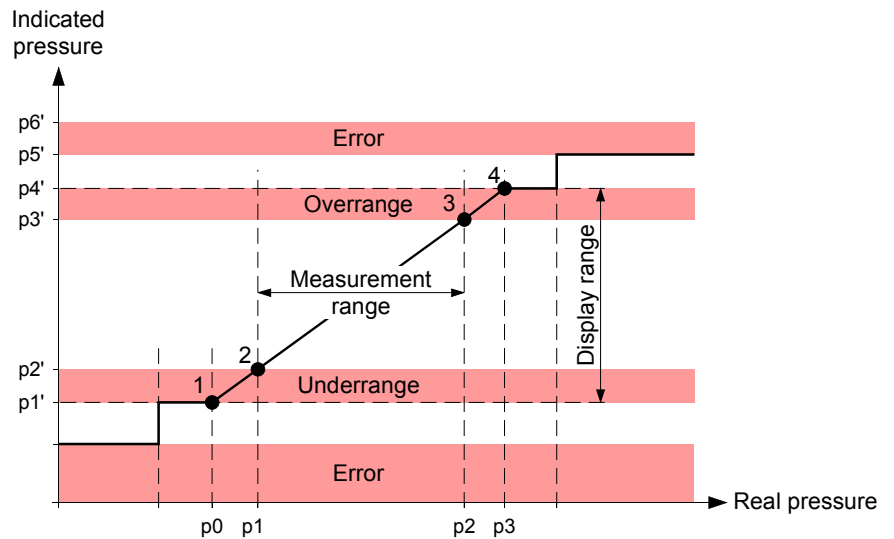
Object index of active source of (I 0x900F SI 0x01) Input Value.

Source Index	
Bit 16...31	Index
Bit 08...15	Subindex
Bit 00...07	Reserved

4.10 PCG with ATM Information Area (0x9000...0x9FFF)

Highest / lowest measurement value

The Information Data object defines the input process data.



The "measurement range" is the range between minimum and maximum pressure, where the reading of the gauge is within the specified measurement uncertainty limits.

The display range is the complete pressure range where the gauge gives an indication (measurement signal). The display range consists of underrange, measurement range and overrange.

According to these definitions, 4 points are defined:

- 1 Lowest informational measurement value
- 2 Lowest precision measurement value
- 3 Highest precision measurement value
- 4 Highest informational measurement value

Index	SI	Data Type	NV	Access	PM	Name
9000	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02

Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03

Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04

Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.10.1 Information Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
9001	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0	0
Bit 1	Electronics Warning
Bit 2...15	0

Subindex 0x02

Sensor Alarms	
Bit 0	Diaphragm Failure
Bit 1	Electronics Failure
Bit 2...15	0

4.10.2 Information Common

Index	SI	DataType	NV	Access	PM	Name
9010	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02

Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03

Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04

Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.10.3 Information Piezo

Index	SI	DataType	NV	Access	PM	Name
9012	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0...15	0

Subindex 0x02

Sensor Alarms	
Bit 0...15	0

4.10.4 Information Common

Index	SI	DataType	NV	Access	PM	Name
9020	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02 Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03 Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04 Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.10.5 Information Heat Transfer

Index	SI	Data Type	NV	Access	PM	Name
9023	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0	0
Bit 1	Electronics Warning
Bit 2...15	0

Subindex 0x02

Sensor Alarms	
Bit 0	0
Bit 1	Electronics Failure
Bit 2...15	0

4.10.6 Information Trip Point 1/2

Index	SI	Data Type	NV	Access	PM	Name
900E	0x01	REAL		RO		Input Value Trip Point 1
900F	0x02	REAL		RO		Input Value Trip Point 2

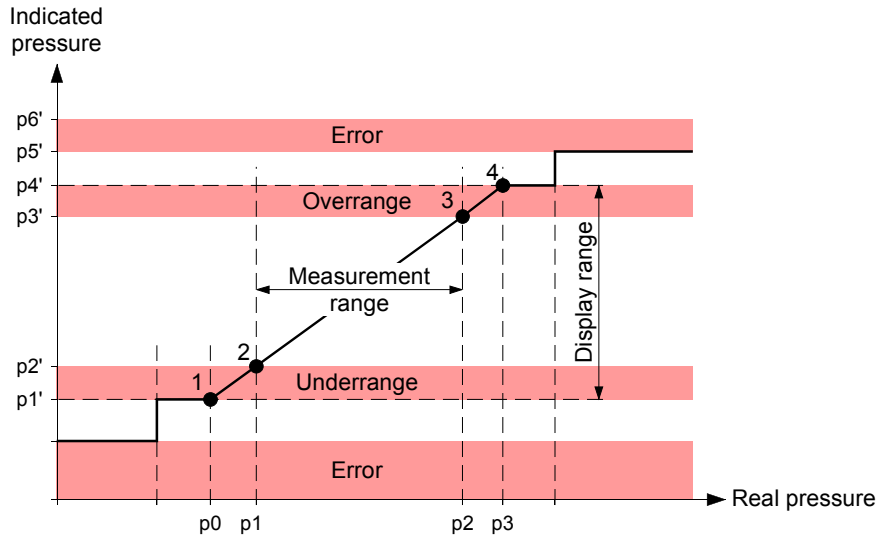
Subindex 0x01 Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x0E).

Subindex 0x02 Input Value Trip Point 2: 0 Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x0E).

4.11 PCG without ATM, Information Area (0x9000...0x9FFF)

Highest / lowest measurement value

The Information Data object defines the input process data.



The "measurement range" is the range between minimum and maximum pressure, where the reading of the gauge is within the specified measurement uncertainty limits.

The display range is the complete pressure range where the gauge gives an indication (measurement signal). The display range consists of underrange, measurement range and overrange.

According to these definitions, 4 points are defined:

- 1 Lowest informational measurement value
- 2 Lowest precision measurement value
- 3 Highest precision measurement value
- 4 Highest informational measurement value

Index	SI	DataType	NV	Access	PM	Name
9000	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02

Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03

Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04

Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.11.1 Information Capacitance Diaphragm

Index	SI	DataType	NV	Access	PM	Name
9001	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0	0
Bit 1	Electronics Warning
Bit 2...15	0

Subindex 0x02

Sensor Alarms	
Bit 0	Diaphragm Failure
Bit 1	Electronics Failure
Bit 2...15	0

4.11.2 Information Common

Index	SI	DataType	NV	Access	PM	Name
9010	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02

Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03

Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04

Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.11.3 Information Heat Transfer

Index	SI	DataType	NV	Access	PM	Name
9013	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0	0
Bit 1	Electronics Warning
Bit 2...15	0

Subindex 0x02

Sensor Alarms	
Bit 0	0
Bit 1	Electronics Failure
Bit 2...15	0

4.11.4 Information Trip Point 1/2

Index	SI	DataType	NV	Access	PM	Name
900E	0x01	REAL		RO		Input Value Trip Point 1
900F	0x02	REAL		RO		Input Value Trip Point 2

Subindex 0x01

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x0E).

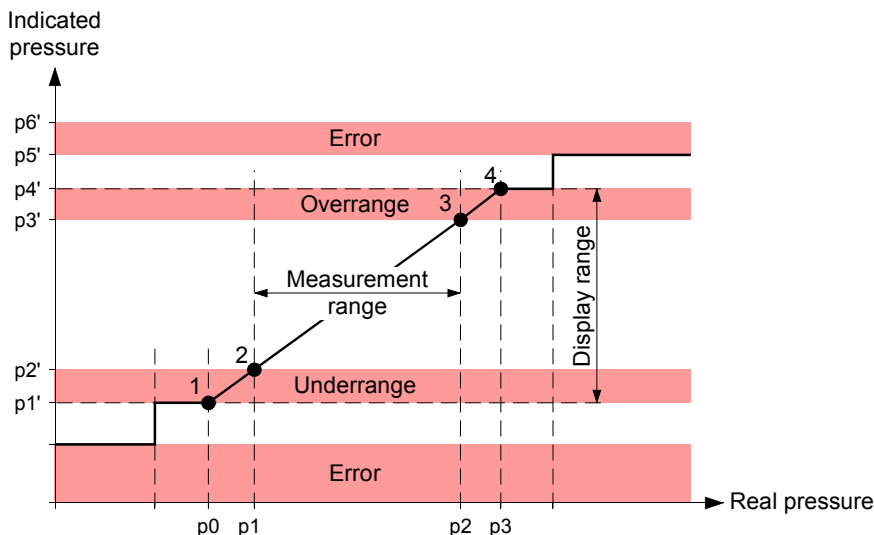
Subindex 0x02

Input Value Trip Point 2: 0 Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x0E).

4.12 PSG Information Area (0x9000...0x9FFF)

Highest / lowest measurement value

The Information Data object defines the input process data.



The "measurement range" is the range between minimum and maximum pressure, where the reading of the gauge is within the specified measurement uncertainty limits.

The display range is the complete pressure range where the gauge gives an indication (measurement signal). The display range consists of underrange, measurement range and overrange.

According to these definitions, 4 points are defined:

- 1 Lowest informational measurement value
- 2 Lowest precision measurement value
- 3 Highest precision measurement value
- 4 Highest informational measurement value

4.12.1 Information Common

Index	SI	Data Type	NV	Access	PM	Name
9000	0x02	REAL	x	RO		Highest Informational Measurement Value
	0x03	REAL	x	RO		Highest Precision Measurement Value
	0x04	REAL	x	RO		Lowest Precision Measurement Value

Subindex 0x02

Highest Informational Measurement Value: Highest value that the gauge can measure without a specified accuracy.

Subindex 0x03

Highest Precision Measurement Value: Highest valid value at which the gauge is specified with an accuracy value. Above that value, the parameter Reading Valid is set to invalid.

Subindex 0x04

Lowest Precision Measurement Value: Lowest valid value at which the gauge is specified with an accuracy value. Below that value, the parameter Reading Valid is set to invalid.

4.12.2 Information Heat Transfer

Index	SI	Data Type	NV	Access	PM	Name
9003	0x01	UINT		RO		Sensor Warning
	0x02	UINT		RO		Sensor Alarm

Subindex 0x01

Sensor Warnings	
Bit 0	0
Bit 1	Electronics Warning
Bit 2...15	0

Subindex 0x02

Sensor Alarms	
Bit 0	0
Bit 1	Electronics Failure
Bit 2...15	0

4.12.3 Information Trip Point 1/2

Index	SI	Data Type	NV	Access	PM	Name
900E	0x01	REAL		RO		Input Value Trip Point 1
900F	0x02	REAL		RO		Input Value Trip Point 2

Subindex 0x01

Input Value Trip Point 1: Trip Point Input value as referenced by Source Index (I 0x800E, SI 0x0E).

Subindex 0x02

Input Value Trip Point 2: 0 Trip Point Input value as referenced by Source Index (I 0x800F, SI 0x0E).

4.13 Device Area (0xF000...0xAFFF)

4.13.1 Semiconductor Device Profile

Index	SI	Data Type	NV	Access	PM	Name
F000	0x01	UINT		RO		Index Distance
	0x02	UINT		RO		Maximum Number of Modules

Subindex 0x01

Index Distance: Index offset between PDO entries of two consecutive modules (for ETG.5003 = 0x10).

Subindex 0x02

Maximum Number of Modules: Up to 255 modules are possible. A device can support less than this. This entry described the supported number of modules.

4.13.2 PCG with ATM Module Profile List

Index	SI	Data Type	NV	Access	PM	Name
F010	0x01	UDINT		RO		Profile Number Module 1
	0x02	UDINT		RO		Profile Number Module 2
	0x03	UDINT		RO		Profile Number Module 3

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x02

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x03

Each sub-index lists the profile-number of the corresponding module.

4.13.3 PCG without ATM, Module Profile List

Index	SI	DataType	NV	Access	PM	Name
F010	0x01	UDINT		RO		Profile Number Module 1
	0x02	UDINT		RO		Profile Number Module 2

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

Subindex 0x02

Each sub-index lists the profile-number of the corresponding module.

4.13.4 PSG Module Profile List

Index	SI	DataType	NV	Access	PM	Name
F010	0x01	UDINT		RO		Profile Number Module 1

Subindex 0x01

Each sub-index lists the profile-number of the corresponding module.

4.14 Exceptions

4.14.1 Active Exception Status

Index	SI	DataType	NV	Access	PM	Name
F380		USINT		RO	tx	ActiveException Status

Active Exception Status

Active Exception Status	
Bit 0	Device Warning
Bit 1	Manufacturer Warning
Bit 2	Device Error
Bit 3	Manufacturer Error
Bit 4...7	0

4.14.2 PCG with ATM Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	DataType	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details Device
	0x02	UDINT		RO	tx	Active Device Warning Details Module 1
	0x03	UDINT		RO	tx	Active Device Warning Details Module 2
	0x04	UDINT		RO	tx	Active Device Warning Details Module 3
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details(Index F381)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (CDG)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x03 (Piezo)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x04 (Pirani)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.3 PCG without ATM, Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	Data Type	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details Device
	0x02	UDINT		RO	tx	Active Device Warning Details Module 1
	0x03	UDINT		RO	tx	Active Device Warning Details Module 2
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details(Index F381)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (CDG)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x03 (Pirani)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.4 PSG Active Device Warning Details

The "active device warning details" parameter describes the warning state of the complete device.

Index	SI	Data Type	NV	Access	PM	Name
F381	0x01	UDINT		RO	tx	Active Device Warning Details Device
	0x02	UDINT		RO	tx	Active Device Warning Details Module 1
F382	0x01	UDINT		RO	tx	Active Manufacturer Warning Details

Subindex 0x01

Active Device Warning Details(Index F381)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (Pirani)

Active Device Warning Details(Index F381)	
Bit 0	0
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Warning Details (Index F382)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.5 PCG with ATM Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	Data Type	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details Device
	0x02	UDINT		RO	tx	Active Device Error Details Module 1
	0x03	UDINT		RO	tx	Active Device Error Details Module 2
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (CDG)

Active Device Error Details (Index F383)	
Bit 0	Diaphragm Failure
Bit 1	Electronics failure
Bit 2...31	0

Subindex 0x03 (ATM)

Active Device Error Details (Index F383)	
Bit 0...31	0

Subindex 0x04 (Pirani)

Active Device Error Details (Index F383)	
Bit 0	Sensor Failure
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.6 PCG without ATM, Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	Data Type	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details Device
	0x02	UDINT		RO	tx	Active Device Error Details Module 1
	0x03	UDINT		RO	tx	Active Device Error Details Module 2
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (CDG)

Active Device Error Details (Index F383)	
Bit 0	Diaphragm Failure
Bit 1	Electronics failure
Bit 2...31	0

Subindex 0x03 (Pirani)

Active Device Error Details (Index F383)	
Bit 0	Sensor Failure
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.7 PSG Active Device Error Details

The "active device error details" parameter describes the error state of the complete device.

Index	SI	Data Type	NV	Access	PM	Name
F383	0x01	UDINT		RO	tx	Active Device Error Details Device
	0x02	UDINT		RO	tx	Active Device Error Details Module 1
F384	0x01	UDINT		RO	tx	Active Manufacturer Error Details

Subindex 0x01

Active Device Error Details (Index F383)	
Bit 0...2	0
Bit 3	EEPROM exception
Bit 4...31	0

Subindex 0x02 (Pirani)

Active Device Error Details (Index F383)	
Bit 0	Sensor Failure
Bit 1	Electronics exception
Bit 2...31	0

Subindex 0x01

Active Manufacturer Error Details (Index F384)	
Bit 0	Internal Communication Exception (between EtherCAT-Protocol and Device-Application)
Bit 1...31	0

4.14.8 PCG with ATM Latched Device Warning Details

Index	SI	Data Type	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details Device
	0x02	UDINT		RO	tx	Latched Device Warning Details Module 1
	0x03	UDINT		RO	tx	Latched Device Warning Details Module 2
	0x04	UDINT		RO	tx	Latched Device Warning Detail Module 3
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01

Latched Device Warning Details Device: Latched version of 0xF381:01.

Subindex 0x02

Latched Device Warning Details Module 1: Latched version of 0xF381:02.

Subindex 0x03

Latched Device Warning Details Module 2: Latched version of 0xF381:03.

Subindex 0x04

Latched Device Warning Details Module 3: Latched version of 0xF381:04.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

4.14.9 PCG without ATM, Latched Device Warning Details

Index	SI	Data Type	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details Device
	0x02	UDINT		RO	tx	Latched Device Warning Details Module 1
	0x03	UDINT		RO	tx	Latched Device Warning Details Module 2
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01

Latched Device Warning Details Device: Latched version of 0xF381:01.

Subindex 0x02

Latched Device Warning Details Module 1: Latched version of 0xF381:02.

Subindex 0x03

Latched Device Warning Details Module 2: Latched version of 0xF381:03.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

4.14.10 PSG Latched Device Warning Details

Index	SI	Data Type	NV	Access	PM	Name
F390		USINT		RO	tx	Latched Exceptions Status
F391	0x01	UDINT		RO	tx	Latched Device Warning Details Device
	0x02	UDINT		RO	tx	Latched Device Warning Detail Module 1
F392	0x01	UDINT		RO	tx	Latched Manufacturer Warning Details

Latched Exceptions Status

Latched version of 0xF380.

Subindex 0x01

Latched Device Warning Details Device: Latched version of 0xF381:01.

Subindex 0x02

Latched Device Warning Details Module 1: Latched version of 0xF381:02.

Subindex 0x01 (F392)

Latched Manufacturer Warning Details: Latched version of 0xF382:01.

4.14.11 PCG with ATM Latched Device Error Details

Index	SI	Data Type	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details Device
	0x02	UDINT		RO	tx	Latched Device Error Details Module 1
	0x03	UDINT		RO	tx	Latched Device Error Details Module 2
	0x04	UDINT		RO	tx	Latched Device Error Details Module 3
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details

Subindex 0x01

Latched Device Error Details Device: Latched version of 0xF383:01.

- Subindex 0x02 Latched Device Error Details Module 1: Latched version of 0xF383:02.
- Subindex 0x03 Latched Device Error Details Module 2: Latched version of 0xF383:03.
- Subindex 0x04 Latched Device Error Details Module 3: Latched version of 0xF383:04.
- Subindex 0x01 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:01.

4.14.12 PCG without ATM, Latched Device Error Details

Index	SI	Data Type	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details Device
	0x02	UDINT		RO	tx	Latched Device Error Details Module 1
	0x03	UDINT		RO	tx	Latched Device Error Details Module 2
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details

- Subindex 0x01 Latched Device Error Details Device: Latched version of 0xF383:01.
- Subindex 0x02 Latched Device Error Details Module 1: Latched version of 0xF383:02.
- Subindex 0x03 Latched Device Error Details Module 2: Latched version of 0xF383:03.
- Subindex 0x01 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:01.

4.14.13 PSG Latched Device Error Details

Index	SI	Data Type	NV	Access	PM	Name
F393	0x01	UDINT		RO	tx	Latched Device Error Details Device
	0x02	UDINT		RO	tx	Latched Device Error Details Module 1
F394	0x01	UDINT		RO	tx	Latched Manufacturer Error Details

- Subindex 0x01 Latched Device Error Details Device: Latched version of 0xF383:01.
- Subindex 0x02 Latched Device Error Details Module 1: Latched version of 0xF383:02.
- Subindex 0x01 (F394) Latched Manufacturer Error Details: Latched version of 0xF384:01.

4.14.14 PCG with ATM Device Warning Mask

Index	SI	Data Type	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask Device
	0x02	UDINT	x	RW		Device Warning Mask Module 1
	0x03	UDINT	x	RW		Device Warning Mask Module 2
	0x04	UDINT	X	RW		Device Warning Mask Module 3
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01

Device Warning Mask Device: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x02

Device Warning Mask Module 1: Mask bits for 0xF381:02 and 0xF391:02.

Subindex 0x03

Device Warning Mask Module 2: Mask bits for 0xF381:03 and 0xF391:03.

Subindex 0x04

Device Warning Mask Module 3: Mask bits for 0xF381:03 and 0xF391:04.

Subindex 0x01 (F3A2)

Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

4.14.15 PCG without ATM, Device Warning Mask

Index	SI	Data Type	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask Device
	0x02	UDINT	x	RW		Device Warning Mask Module 1
	0x03	UDINT	x	RW		Device Warning Mask Module 2
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01

Device Warning Mask Device: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x02

Device Warning Mask Module 1: Mask bits for 0xF381:02 and 0xF391:02.

Subindex 0x03

Device Warning Mask Module 2: Mask bits for 0xF381:03 and 0xF391:03.

Subindex 0x01 (F3A2)

Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

4.14.16 PSG Device Warning Mask

Index	SI	Data Type	NV	Access	PM	Name
F3A1	0x01	UDINT	x	RW		Device Warning Mask Device
	0x02	UDINT	x	RW		Device Warning Mask Module 1
F3A2	0x01	UDINT	x	RW		Manufacturer Warning Mask

Subindex 0x01

Device Warning Mask Device: Mask bits for 0xF381:01 and 0xF391:01.

Subindex 0x02

Device Warning Mask Module 1: Mask bits for 0xF381:02 and 0xF391:02.

Subindex 0x01 (F3A2)

Manufacturer Warning Mask: Mask bits for 0xF382:01 and 0xF392:01.

4.14.17 PCG with ATM Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask Device
	0x02	UDINT	x	RW		Device Error Mask Module 1
	0x03	UDINT	x	RW		Device Error Mask Module 2
	0x04	UDINT	x	RW		Device Error Mask Module 3
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01

Device Error Mask Device: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x02

Device Error Mask Module 1: Mask bits for 0xF383:02 and 0xF393:02.

Subindex 0x03

Device Error Mask Module 2: Mask bits for 0xF383:03 and 0xF393:03.

Subindex 0x04

Device Error Mask Module 3: Mask bits for 0xF383:03 and 0xF393:04.

Subindex 0x01 (F3A4)

Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

4.14.18 PCG without ATM Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask Device
	0x02	UDINT	x	RW		Device Error Mask Module 1
	0x03	UDINT	x	RW		Device Error Mask Module 2
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01

Device Error Mask Device: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x02

Device Error Mask Module 1: Mask bits for 0xF383:02 and 0xF393:02.

Subindex 0x03

Device Error Mask Module 2: Mask bits for 0xF383:03 and 0xF393:03.

Subindex 0x01 (F3A4)

Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

4.14.19 PSG Device Error Mask

Index	SI	DataType	NV	Access	PM	Name
F3A3	0x01	UDINT	x	RW		Device Error Mask Device
	0x02	UDINT	x	RW		Device Error Mask Module 1
F3A4	0x01	UDINT	x	RW		Manufacturer Error Mask

Subindex 0x01

Device Error Mask Device: Mask bits for 0xF383:01 and 0xF393:01.

Subindex 0x02

Device Error Mask Module 1: Mask bits for 0xF383:02 and 0xF393:02.

Subindex 0x01 (F3A4)

Manufacturer Error Mask: Mask bits for 0xF384:01 and 0xF394:01.

4.15 Manufacturer-device specific Profile Objects (0xF500...0xF5FF)

The manufacturer-specific profile objects contain the manufacturer's model number and device configuration data, status and diagnostic data. The objects are described in the following tables.

4.15.1 Manufacturer Device Information

Index	SI	Data Type	NV	Access	PM	Name
F500		V_STRING		RO		Manufacturer's Model Number
F501		V_STRING		RO		Device Configuration

Device Configuration Meaning:

Shortcut	Meaning	Example
DS9	D-Sub 9-pin	DS15HD
FCC	FCC	
HM	Hirschmann	
DS15HD	D-Sub 15-pin. HD	
SP	Setpoint	SP
PS	Potential separation	PS
WO or NI	Filament Tungsten / Nickel	WO
ATM	ATM	ATM
DIS	Display	DIS
DN	DeviceNet	DN
PB	Profibus	
RS1	RS485 I	
RS2	RS485 II	
RS3	RS485 III	
RS4	RS485 IV	
CDG	CDG	CDG
AO0	Characteristic	AO0
AO1	Characteristic	
AO3	Characteristic	
TTR21X	TTR21x Compatibility	TTR21X
PIR	Pirani	PIR
EC	EtherCAT	EC

4.16 Gauge General

4.16.1 Combination Gauge

Index	SI	DataType	NV	Access	PM	Name
F640	0x01	BOOL		RO	tx	Combination Gauge Reading Valid
	0x02	BOOL		RO	tx	Combination Gauge Overrange Exceeded
	0x03	BOOL		RO	tx	Combination Gauge Underrange Exceeded
	0x11	REAL		RO	tx	Combination Gauge Active Value
	0x12	UINT		RO	tx	Combination Gauge Active Sensor Number

Subindex 0x01

Identifies whether the complete vacuum pressure gauge (with several measuring principles) is out of its absolute overrange or absolute underrange, or in any other failure condition.

Subindex 0x02

If the bit "Overrange" is set, all instances of the gauge are in an overrange condition.

Subindex 0x03

If the bit "Underrange" is set, all instances of the gauge are in an underrange condition

Subindex 0x11

The value copied from the measurement value of the active measuring instance used for the Input PDO.

Subindex 0x12

Identifies the object instance that is providing the measurement value, the latter of which is copied into the Active Value parameter for all Input PDO's.

4.16.2 Trip Point Output All

Index	SI	DataType	NV	Access	PM	Name
F641	0x01	UDINT		RO	tx	Trip Point Output All Instance

Subindex 0x01

Status of Trip Point instances.

Trip Point Output All Instance	
Bit 0	Status High Trip (I 0x600E, SI 0x01)
Bit 1	Status Low Trip (I 0x600E S, I 0x02)
Bit 2	Status High Trip (I 0x600F, SI 0x01)
Bit 3	Status Low Trip (I 0x600F, SI 0x02)
...	...
Bit 30	Status High Trip (I 0x608F, SI 0x01)
Bit 31	Status Low Trip (I 0x608F, SI 0x02)

4.16.3 Input Latch Local Timestamp

Index	SI	Data Type	NV	Access	PM	Name
F6F0	0x01	UDINT		RO	tx	Input Latch Local Timestamp. Mandatory if device has inputs (TxPDOs)
	0x02	UDINT		RO	tx	Input Latch Local Timestamp. Mandatory if device has inputs (TxPDOs)
	0x03	UDINT		RO	tx	Input Latch Local Timestamp. Mandatory if device has inputs (TxPDOs)

Subindex 0x01

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x02

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

Subindex 0x03

Local controller time corresponding to the input latch time in microseconds. It starts at zero on device power-up. Mandatory if device has inputs. If device has no inputs defined, this corresponds the time immediately prior to writing to input SM.

4.17 Configure Device

Index	SI	Data Type	NV	Access	PM	Name
F840	0x01	UDINT	x	RW		Data Units

Subindex 0x01

Unit of the Value of the Analog Input Sensor Instance and all related parameters.

Trip Point Output All Instance	
0x00220000	Pascal
0xFD4E0000	mbar
0x00A10000	Torr
0x00E00000	Counts (INFICON)

4.18 Information

4.18.1 PCG with ATM Information Device

Index	SI	Data Type	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
	0x04	V_STRING	x	RO		SW Version VPG PCB
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number Module 1
	0x02	UDINT		RO		CDP Functional Generation Number Module 2
	0x03	UDINT		RO		CDP Functional Generation Number Module 3
F9F2	0x01	UDINT		RO		SDP Functional Generation Number Module 1
	0x02	UDINT		RO		SDP Functional Generation Number Module 2
	0x03	UDINT		RO		SDP Functional Generation Number Module 3
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name Module 1
	0x02	V_STRING		RO		Semiconductor SDP Device Name Module 2
	0x03	V_STRING		RO		Semiconductor SDP Device Name Module 3
F9F5	0x01	USINT		RW	rx/tx	Output Identifier Module 1
	0x02	USINT		RW	rx/tx	Output Identifier Module 2
	0x03	USINT		RW	rx/tx	Output Identifier Module 3
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

4.18.2 PCG without ATM, Information Device

Index	SI	DataType	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
	0x04	V_STRING	x	RO		SW Version VPG PCB
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number Module 1
	0x02	UDINT		RO		CDP Functional Generation Number Module 2
F9F2	0x01	UDINT		RO		SDP Functional Generation Number Module 1
	0x02	UDINT		RO		SDP Functional Generation Number Module 2
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name Module 1
	0x02	V_STRING		RO		Semiconductor SDP Device Name Module 2
F9F5	0x01	USINT		RW	rx/tx	Output Identifier
	0x01	USINT		RW	rx/tx	Output Identifier
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

4.18.3 PSG Information Device

Index	SI	DataType	NV	Access	PM	Name
F940	0x01	UDINT		RO		Measurement Principle
	0x02	BYTE		RO		Number of Sensors
	0x04	V_STRING	x	RO		SW Version VPG PCB
F9F0		V_STRING		RO		Manufacturer Serial Number
F9F1	0x01	UDINT		RO		CDP Functional Generation Number Module 1
F9F2	0x01	UDINT		RO		SDP Functional Generation Number Module 1
F9F3		V_STRING		RO		Vendor Name
F9F4	0x01	V_STRING		RO		Semiconductor SDP Device Name Module 1
F9F5	0x01	USINT		RW	rx/tx	Output Identifier
F9F6		UDINT		RO		Time since power on
F9F7		UDINT	x	RO		Total time powered
F9F8		UDINT		RO		Firmware Update Functional Generation Number

Subindex 0x01 (F940)

Measurement principle assigned to the object instance.

The most significant nibble of the parameter represents the sensor type of the first module, the second most significant nibble of the parameter represents the sensor type of the second Module, and so forth.

Measurement Principle (Index F940)	
1	Capacitance Manometer
2	Piezo
3	Pirani
4	Cold Cathode
5	Hot Cathode

Subindex 0x02 (F940)

Number of Sensors (Index F940): The number of sensors implemented on the device.

Subindex 0x04 (F940)

If the device consists out of several software portions this parameter should be used.

Using standard a.b.c.d format to describe a version:

SW Version VPG PCB (Index F940)	
a	Mayor revision
b	Minor revision
c	Development revision
d	Vendor specific
i.e. 1.0.1.2	

4.19 Adjust and Reset

4.19.1 Command Zero Adjust

Execution of this command will start a Zero Adjust operation.

Index	SI	DataType	NV	Access	PM	Name
FB40	0x01	V_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	V_STRING(3)		RO		Response

Subindex 0x01

Command	
Byte 0	0: Zero adjust with no offset
Byte 1	1: Index of the Sub Sensor (always 1)
Byte 2...5	0: Offset value (Data format: REAL, always 0)

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	Unused
Byte 2	0: Zeroing successful 1: Zeroing failed; out-of-range 2: Zeroing failed; cumulative out-of-range 3: Zeroing failed: measurement invalid 254: No previous Zero Adjust command issued

4.19.2 Full Scale Adjust

Execution of this command will start a Full Scale Adjust operation.

Index	SI	Data Type	NV	Access	PM	Name
FB41	0x01	V_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	V_STRING(3)		RO		Response

Subindex 0x01

Command	
Byte 0	0: Full Scale Adjust
Byte 1	2: Index of the Sub Sensor Instance (always 2)
Byte 2...5	Full Scale value (Data format: REAL, always 0)

Subindex 0x02

Status (supported values)	
0	Last command completed, no errors, no reply available
1	Last command completed, no errors, reply available
2	Last command completed, errors present, no reply available
3	Last command completed, errors present, reply available
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	Unused
Byte 2	0: Full Scale Adjust successful 1: Full Scale Adjust failed: out-of-range 254: No previous Full Scale Adjust command issued

4.19.3 Device Reset Command

Execution of this command causes the device to emulate a complete power cycle. This includes an ESC reset. An SDP may limit some behavior of the power cycle emulation, but shall not exclude the EtherCAT interface.



As consequence of an ESC reset all following devices are disconnected from the network.

There are two versions of this command:

- Standard reset (as described above)
- Factory reset (as described above, but additionally, all parameters are restored to as-shipped defaults).

Index	SI	Data Type	NV	Access	PM	Name
FBF0	0x01	V_STRING(6)		RW		Command
	0x02	BYTE		RO		Status
	0x03	V_STRING(1)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72
Byte 5	0x00 = Standard reset, 0x66 = Factory Reset

Subindex 0x02

Status (supported values)	
0	Reserved
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	Unused
Byte 2...n	Unused

4.19.4 Exception Reset Command

Execution of this command clears the latched exceptions.

Index	SI	Data Type	NV	Access	PM	Name
FBF1	0x01	V_STRING(5)		RW		Command
	0x02	BYTE		RO		Status
	0x03	V_STRING(1)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x74
Byte 1	0x65
Byte 2	0x73
Byte 3	0x65
Byte 4	0x72

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02
Byte 1	Unused
Byte 2...n	Unused

4.19.5 Store Parameters Command

Execution of this command will store all parameters to non-volatile memory. If a device automatically saves all non-volatile parameters at the time they are set, this command will not take any action.

Index	SI	Data Type	NV	Access	PM	Name
FBF2	0x01	V_STRING(4)		RW		Command
	0x02	BYTE		RO		Status
	0x03	V_STRING(1)		RO		Response

Subindex 0x01

A device reset is initiated when the following byte sequence is sent.

Command	
Byte 0	0x65
Byte 1	0x76
Byte 2	0x61
Byte 3	0x73

Subindex 0x02

Status (supported values)	
0	Last command completed, no error, no response
1	Reserved
2	Last command completed, error, no response
3	Reserved
255	Command is executing

Subindex 0x03

Response	
Byte 0	See Subindex 0x02

Appendix

A: Literature

- [1] www.inficon.com
Operating Manual
PCG550, PCG552, PCG554
tina56d1 (German)
tina56e1 (English)
INFICON AG, LI-9496 Balzers, Liechtenstein
- [2] www.inficon.com
Operating Manual
PSG550, PSG552, PSG554
tina60d1 (German)
tina60e1 (English)
INFICON AG, LI-9496 Balzers, Liechtenstein
- [3] ETG.1000.2: Physical Layer service definition and protocol specification
- [4] ETG.1000.3: Data Link Layer service definition
- [5] ETG.1000.4: Data Link Layer protocol specification
- [6] ETG.1000.5: Application Layer service definition
- [7] ETG.1000.6: Application Layer protocol specification
- [8] ETG.1020: EtherCAT Protocol Enhancements
- [9] ETG.2000: EtherCAT Slave Information
- [10] ETG.5001.1: Modular Device Profile – Part 1: General MDP Device Model
- [11] ETG.5003.1: Semiconductor Device profile – Part 1: Common Device Profile (CDP)
- [12] ETG.5003.2080: Semiconductor Device profile – Part 2080: Specific Device Profile (SDP): Vacuum Pressure Gauge
- [13] IEC 61158-x-12 (all parts for type 12): Industrial communication networks – Fieldbus specifications
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- [15] SEMI E54 / Draft 5102A: SPECIFICATION FOR SENSOR/ACTUATOR NETWORK SPECIFIC DEVICE MODEL FOR VACUUM PRESSURE GAUGES
- [16] SEMI E52: Practice for referencing gases, gas mixtures and vaporizable materials used in digital mass flow controllers

Notes

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